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# EIGENVALUES AND EIGENVECTORS FOR THE QUATERNION MATRICES OF DEGREE TWO

## **Cristina Flaut**

#### Abstract

In this paper we give a computation method, in a particular case, for eigenvalues and eigenvectors of the quaternion matrices of degree two with elements in the generalized quaternion division algebra  $\mathbb{H}(\alpha, \beta)$ . It is known (see[1]) that every quaternion matrix has at least one characteristic root, but there is not yet giving a computing method. By using [4] we give such a computing method for eigenvalues and eigenvectors of the quaternion matrices of degree two with elements in the generalized quaternion division algebra  $\mathbb{H}(\alpha, \beta)$ .

Let  $\mathbb{H}(\alpha, \beta)$  be the generalized quaternion division algebra over the comutative field K with char  $K \neq 2$ .

**Definition 1** Let  $A \in \mathcal{M}_n(\mathbb{H}(\alpha, \beta))$  and  $\lambda \in \mathbb{H}(\alpha, \beta)$ . The quaternion  $\lambda$  is called an **eigenvalue** of the matrix A (or a **characteristic root**), if there exists a matrix  $x \in \mathcal{M}_{n \times 1}(\mathbb{H}(\alpha, \beta))$ ,  $x \neq 0$ , such that  $Ax = x\lambda$ . The matrix x is called the **eigenvector** of the matrix A.

**Proposition 1** Two similar matrices have the same characteristic roots.

**Proof.** Let  $A \sim B$ , i.e. there exists an invertible matrix  $T \in \mathcal{M}_n(\mathbb{H}(\alpha,\beta))$ such that  $B = TAT^{-1}$ . Let  $\lambda \in \mathbb{H}(\alpha,\beta)$  be an eigenvalue for the matrix A, then we find the matrix  $x \in \mathcal{M}_{n \times 1}(\mathbb{H}(\alpha,\beta))$  such that  $Ax = x\lambda, x \neq 0$ . Let y = Tx. Then  $By = TAT^{-1}y = TAx = Tx\lambda = y\lambda$ .

**Proposition 2** Let  $A \in \mathcal{M}_n(\mathbb{H}(\alpha,\beta))$  and let  $\lambda \in \mathbb{H}(\alpha,\beta)$  be an eigenvalue of the matrix A. If  $\rho \in \mathbb{H}(\alpha,\beta)$ ,  $\rho \neq 0$ , then  $\rho^{-1}\lambda\rho$  is also an eigenvalue of the matrix A.

Key Words: quaternion matrices; generalized quaternion algebra.

**Proof.** From  $Ax = x\lambda$ , we get  $A(x\rho) = x\lambda\rho = (x\rho)\rho^{-1}\lambda\rho.\Box$ 

**Remark 1** From the Proposition 2, we see that, if the vector corresponding to the eigenvalue  $\lambda$  is x, then  $x\rho$  is the eigenvector corresponding to the characteristic root  $\rho^{-1}\lambda\rho$ .

**Proposition 3** ([1])Let K be an arbitrary field, not necessarily commutative, with char  $K \neq 2$ . If  $A = (a_{ij})_{i,j=\overline{1,n}} \in \mathcal{M}_n(K)$ , then we have a triangular invertible matrix T such that  $C = T^{-1}AT$ ,  $C = (c_{ij})_{i,j=\overline{1,n}}$ , where  $c_{ij} = 0$ , for all i > j + 1,  $i, j \in \{1, 2, ..., n\}$ .

Let  $\mathbb{H}$  be the real quaternion algebra and let f be the polynomial of degree n:

 $f\left(X\right) = a_0 X a_1 X \dots X a_n + g\left(X\right),$ 

where  $a_0, a_1, ..., a_n \in \mathbb{H}$ ,  $a_i \neq 0$  for every  $i = \overline{1, n}$  and g(X) is a finite sum of monomials of the form  $b_0Xb_1X...Xb_m$ , where  $m \leq n$ .

In [2], it is shown that, if the polynomial f has a single term of degree n, then the equation f(x) = 0 has exactly n solutions in  $\mathbb{H}$ .

**Proposition 4** ([1])Let  $A \in \mathcal{M}_n(\mathbb{H})$ , then the matrix A has an eigenvalue.

In the next, let  $\mathbb{H}(\alpha,\beta)$  be the generalized quaternion division algebra over

the commutative field K with char  $K \neq 2$ . It is known that  $\mathbb{H}(\alpha, \beta)$  is an algebra of degree two, then every element  $x \in \mathbb{H}(\alpha, \beta)$  satisfies a relation of the form:

$$x^{2} + t(x)x + n(x) = 0,$$

where  $t(x), n(x) \in K$  are the **trace** and the **norm** of the element x.

If  $\{1, e_1, e_2, e_3\}$  is a basis in  $\mathbb{H}(\alpha, \beta)$  and  $x \in \mathbb{H}(\alpha, \beta)$ , then, for  $x = a + be_1 + ce_2 + de_3$ , the element  $\bar{x} = a - be_1 - ce_2 - de_3$  is called the **conjugate** of the element x and we have the relations:

$$x + \bar{x} = t(x)$$
 and  $x\bar{x} = n(x)$ 

**Proposition 5** ([4]) Let  $a, b \in \mathbb{H}(\alpha, \beta)$ ,  $a \neq 0, b \neq 0$ . Then the linear equation

$$ax = xb \tag{5.1.}$$

has nonzero solutions,  $x \in \mathbb{H}(\alpha, \beta)$ , if and only if :

$$t(a) = t(b) \text{ and } n(a - a_0) = n(b - b_0),$$
 (5.2.)

where  $a = a_0 + a_1e_1 + a_2e_2 + a_3e_3, b = b_0 + b_1e_1 + b_2e_2 + b_3e_3.$ 

**Proposition 6** ([4]) *i*) If  $a = a_0 + a_1e_1 + a_2e_2 + a_3e_3$ ,  $b = b_0 + b_1e_1 + b_2e_2 + b_3e_3 \in \mathbb{H}(\alpha, \beta)$  with  $b \neq \bar{a}$ ,  $a, b \notin K$ , then the solutions of the equation (5.1.), with t(a) = t(b) and  $n(a - a_0) = n(b - b_0)$ , are found in  $\mathcal{A}(a, b)$  (the algebra generated by the elements a and b) and have the form :

$$x = \lambda_1 (a - a_0 + b - b_0) + \lambda_2 \left( n \left( a - a_0 \right) - \left( a - a_0 \right) \left( b - b_0 \right) \right), \tag{6.1.}$$

where  $\lambda_1, \lambda_2 \in K$  are arbitrary.

ii) If  $b = \bar{a}$ , then the general solution of the equation (5.1.) is  $x = x_1e_1 + x_2e_2 + x_3e_3$ , where  $x_1, x_2, x_3 \in K$  and they satisfy the identity :

$$\alpha a_1 x_1 + \beta a_2 x_2 + \alpha \beta a_3 x_3 = 0. \Box \tag{6.2.}$$

**Proposition 7** ([4]) Let  $a \in \mathbb{H}(\alpha, \beta)$ ,  $a \notin K$ . If there exists  $r \in K$  such that  $n(a)=r^2$ , then  $a = \bar{q}rq^{-1}$ , where  $q = r + \bar{a}$ ,  $q^{-1} = \frac{\bar{q}}{n(q)}$ .

**Proof.** By hypothesis we have  $a(r + \bar{a}) = ar + a\bar{a} = ar + n(a) = ar + r^2 = (a + r)r$ . From  $\bar{q} = r + a$  it results  $\bar{q}r = aq.\Box$ 

**Proposition 8** ([4]) Let  $a \in \mathbb{H}(\alpha, \beta)$  with  $a \notin K$ , if there exist  $r, s \in K$  with the properties  $n(a) = r^4$ ,  $n(r^2 + \bar{a}) = s^2$ , then the quadratic equation  $x^2 = a$  has two solutions of the form:  $x = \pm \frac{r(r^2 + a)}{s}$ .

**Proof.** By Proposition 7, it results that a has the form  $a = \bar{q}r^2q^{-1}$ , where  $q = r^2 + \bar{a}$ . Because  $q^{-1} = \frac{\bar{q}}{n(q)}$ , we obtain  $a = r^2\bar{q}q^{-1} = r^2\bar{q}\frac{\bar{q}}{n(q)} = r^2\frac{\bar{q}^2}{s^2} = \left(\frac{r}{s}\bar{q}\right)^2$ , therefore  $x_1 = \frac{r}{s}\bar{q}, x_2 = -\frac{r}{s}\bar{q}$ 

are the claimed solutions.  $\Box$ 

**Proposition 9** ([4]) Let  $a, b, c \in \mathbb{H}(\alpha, \beta)$  such that ab and  $b^2 - c$  do not belong to K. If ab and  $b^2 - c$  satisfy the conditions in Proposition 8, then the equations xax = b and  $x^2 + bx + xb + c = 0$  have solutions.

**Proof.**  $xax = b \iff (ax)^2 = ab$  and  $x^2 + bx + xb + c = 0 \iff (x+b)^2 = b^2 - c.\Box$ 

**Proposition 10** ([4]) If  $b, c \in \mathbb{H}(\alpha, \beta) \setminus \{K\}$  satisfy the conditions bc=cb,  $\frac{b^2}{4} - c \neq 0$  and there exists  $r \in K$  such that  $n\left(\frac{b^2}{4} - c\right) = r^4$  and  $n\left(r^2 + \frac{\bar{b}^2}{4} - \bar{c}\right) = s^2, s \neq 0$ , then the equation

$$x^2 + bx + c = 0 \tag{10.1}$$

has solutions in  $\mathbb{H}(\alpha,\beta)$ .

**Proof.** Let  $x_0 \in \mathbb{H}(\alpha, \beta)$  be a solution of the equation (10.1.). Because  $x_0^2 = t(x_0) x_0 - n(x_0)$  si  $x_0^2 + bx_0 + c = 0$ , it results that  $t(x_0) x_0 - n(x_0) + bx_0 + c = 0$ , therefore  $(t(x_0) + b) x_0 = c + n(x_0)$ .

Because  $t(x_0)+b \neq 0$ ,  $t(x_0)$ ,  $n(x_0) \in K$ ,  $1 \in \mathcal{A}(b, c)$ , we have

 $t(x_0) + bc$  şi  $c + n(x_0) \in \mathcal{A}(b, c)$ .

Therefore  $x_0 \in \mathcal{A}(b,c)$ . Because bc = cb, we obtain that  $\mathcal{A}(b,c)$  is commutative, therefore  $x_0$  commutes with every element of  $\mathcal{A}(b,c)$ . Then the equation (10.1.) can be written:

$$\left(x+\frac{b}{2}\right)^2 - \frac{b^2}{4} + c = 0$$

and we use Proposition 8.  $\Box$ 

We consider now the case n = 2, hence we take  $A = (a_{ij})_{i,j=\overline{1,2}} \in \mathbb{H}(\alpha,\beta)$ . **Case I.** Let  $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in \mathbb{H}(\alpha,\beta)$  with  $a_{21} \neq 0$ . Let  $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \neq 0$  be the eigenvector corresponding to the eigenvalue  $\lambda$  of the matrix A. We suppose that  $x_2 \neq 0$ . Then the vector  $xx_2^{-1} = \begin{pmatrix} x_1x_2^{-1} \\ 1 \end{pmatrix}$  is the eigenvector corresponding to the eigenvalue  $x_2\lambda x_2^{-1}$  for the matrix A. Therefore we have got an eigenvector of the form  $x = \begin{pmatrix} x_1 \\ 1 \end{pmatrix}$ . Then the relation  $Ax = x\lambda$  is equivalent to the next system:

$$\begin{cases} a_{11}x_1 + a_{12} = x_1\lambda \\ a_{21}x_1 + a_{22} = \lambda \end{cases}$$
(\*)

We replace  $\lambda$  from the second equation in the first one and we get:  $a_{11}x_1+a_{12}=x_1(a_{21}x_1+a_{22})$ , hence  $x_1a_{21}x_1+x_1a_{22}-a_{11}x_1-a_{12}=0$ . We multiply this last relation to the left side with  $a_{21}$ . It results  $a_{21}x_1a_{21}x_1+a_{21}x_1a_{22}-a_{21}a_{11}x_1-a_{21}a_{12}=0$ . We denote  $a_{21}x_1=t$  and we obtain

$$t^{2} + ta_{22} - a_{21}a_{11}a_{21}^{-1}t - a_{21}a_{12} = 0.$$
(\*\*)

If  $a_{22} = -a_{21}a_{11}a_{21}^{-1} = b$ , we denote  $c = -a_{21}a_{12}$ , and if,  $b^2 - c \notin K$  and there exist  $r, s \in K$  with the properties  $n(b^2 - c) = r^4$  and  $n(r^2 + \overline{b^2 - c}) = s^2$ , then we may use the *Proposition 8* getting  $(t+b)^2 = b^2 + a_{21}a_{12}$ , therefore:  $t = \pm \frac{r}{s}(r^2 + b^2 - c) - b$ .

It results that  $a_{21}x_1 = \pm \frac{r}{s}(r^2 + b^2 - c) - b$  hence  $a_{21}x_1 = \pm \frac{r}{s}(r^2 + a_{21}a_{11}^2a_{21}^{-1} + a_{21}a_{12}) + a_{21}a_{11}a_{21}^{-1}$ . Therefore

$$x_1 = \pm \frac{r}{s} \left( r^2 a_{21}^{-1} + a_{11}^2 a_{21}^{-1} + a_{12} \right) + a_{11} a_{21}^{-1},$$

and, for the eigenvalue  $\lambda$ , we have the expression:

$$\lambda = \pm \frac{r}{s} \left( r^2 + a_{22}^2 + a_{21} a_{12} \right),$$

because  $a_{22} = -a_{21}a_{11}a_{21}^{-1}$  and  $a_{21}a_{21}^2a_{21}^{-1} = a_{21}a_{11}a_{11}a_{21}^{-1} = -a_{22}a_{21}a_{11}a_{21}^{-1} = a_{22}^2$ .

**Case II.** If  $a_{22} \neq -a_{21}a_{11}a_{21}^{-1}, a_{21} \neq 0$ , then the equation (\*\*) is written  $(t + a_{22})^2 - a_{22}^2 - a_{22}t - a_{21}a_{11}a_{21}^{-1}t - a_{21}a_{12} = 0$ . Equivalently, we get:  $(t + a_{22})^2 - (a_{22} + a_{21}a_{11}a_{21}^{-1})(t + a_{22}) + a_{21}a_{11}a_{21}^{-1}a_{22} - a_{21}a_{12} = 0$ . Denoting  $-(a_{22} + a_{21}a_{11}a_{21}^{-1}) = b, a_{21}a_{11}a_{21}^{-1}a_{22} - a_{21}a_{12} = c$  and  $t + a_{22} = v$ , we obtain the equation:

$$v^2 + bv + c = 0. \tag{***}$$

If  $b, c \in \mathbb{H}(\alpha, \beta) \setminus \{K\}$ , bc=cb,  $\frac{b^2}{4} - c \neq 0$  and there exists  $r \in K$  such that  $n\left(\frac{b^2}{4} - c\right) = r^4$  and  $n\left(r^2 + \frac{\bar{b}^2}{4} - \bar{c}\right) = s^2$ ,  $s \neq 0$ , we may use *Proposition 10* and we obtain the solutions. If these conditions are not satisfied, we can say only that the solutions of the equation (\* \* \*) are in the algebra generated by b and c.

**Case III.** If  $a_{21} = 0$ , and  $a_{12} \neq 0$ , then the vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  is the eigenvector for the eigenvalue  $\lambda = a_{11}$ . If  $a_{21} = 0$  and  $a_{12} = 0$ , we have  $a_{22} = \lambda$  and

then the system (\*) is equivalent to the equation  $a_{11}x_1 = a_{22}x_1$  and its nonzero solutions are given by *Proposition 6*. If we have  $t(a_{11}) = t(a_{22})$ and  $n(a'_{11}) = n(a'_{22})$ , where  $a'_{11} = a_{11} - t(a_{11})$  and  $a'_{22} = a_{22} - t(a_{22})$ , then the solutions have the form (6.1.) for  $a_{11} \neq \bar{a}_{22}$  or have the form (6.2.) for  $a_{11} = \bar{a}_{22}$ .

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"Ovidius" University of Constanta Department of Mathematics and Informatics, 900527 Constanta, Bd. Mamaia 124 Romania e-mail: cflaut@univ-ovidius.ro