



Warped product pseudo-slant submanifolds of nearly Kaehler manifolds

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Abstract

In this paper, we study warped product pseudo-slant submanifolds of nearly Kaehler manifolds. We prove the non-existence results on warped product submanifolds of a nearly Kaehler manifold.

1 Introduction

Slant submanifolds of an almost Hermitian manifold were defined by B.Y. Chen [3] as a natural generalization of both holomorphic and totally real submanifolds. Since then many researchers have studied these submanifolds in complex as well as contact setting [2, 8]. The notion of semi-slant submanifolds of an almost Hermitian manifold was introduced by N. Papaghiuc [9], and is in fact a generalization of CR-submanifolds. Pseudo-slant submanifolds were introduced by A. Carriazo [2] as a special case of bi-slant submanifolds.

Recently, B. Sahin [10] introduced the notion of warped product hemi-slant (pseudo-slant) submanifolds of Kaehler manifolds. He showed that there does not exist any warped product hemi-slant submanifolds in the form $M_{\perp} \times_f M_{\theta}$. He considered warped product hemi-slant submanifolds in the form $M_{\theta} \times_f M_{\perp}$ where M_{\perp} is a totally real submanifold and M_{θ} is a proper slant submanifold of a Kaehler manifold, and gave some examples for their existence. In this paper we prove that there do not exist warped product submanifolds of the types $N_{\perp} \times_f N_{\theta}$ and $N_{\theta} \times_f N_{\perp}$ in a nearly Kaehler manifold \bar{M} , where N_{\perp} is a totally real submanifold and N_{θ} is a proper slant submanifold of \bar{M} .

Key Words: Warped product, slant submanifold, pseudo-slant submanifold, nearly Kaehler manifold
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2 Preliminaries

Let \bar{M} be an almost Hermitian manifold with almost complex structure J and a Riemannian metric g such that

$$(a) \quad J^2 = -I, \quad (b) \quad g(JX, JY) = g(X, Y) \quad (2.1)$$

for all vector fields X, Y on \bar{M} .

Further let $T\bar{M}$ denote the tangent bundle of \bar{M} and $\bar{\nabla}$, the covariant differential operator on \bar{M} with respect to g . If the almost complex structure J satisfies

$$(\bar{\nabla}_X J)X = 0 \quad (2.2)$$

for any $X \in T\bar{M}$, then the manifold \bar{M} is called a *nearly Kaehler manifold*. Equation (2.2) is equivalent to $(\bar{\nabla}_X J)Y + (\bar{\nabla}_Y J)X = 0$. Obviously, every Kaehler manifold is nearly Kaehler manifold.

For a submanifold M of a Riemannian manifold \bar{M} , the Gauss and Weingarten formulae are respectively given by

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y) \quad (2.3)$$

and

$$\bar{\nabla}_X N = -A_N X + \nabla_X^\perp N \quad (2.4)$$

for all $X, Y \in TM$, where ∇ is the induced Riemannian connection on M , N is a vector field normal to \bar{M} , h is the second fundamental form of M , ∇^\perp is the normal connection in the normal bundle $T^\perp M$ and A_N is the shape operator of the second fundamental form. They are related as in [11] by

$$g(A_N X, Y) = g(h(X, Y), N) \quad (2.5)$$

where g denotes the Riemannian metric on \bar{M} as well as the metric induced on M . The mean curvature vector H of M is given by

$$H = \frac{1}{n} \sum_{i=1}^n h(e_i, e_i) \quad (2.6)$$

where n is the dimension of M and $\{e_1, e_2, \dots, e_n\}$ is a local orthonormal frame of vector fields on M .

A submanifold M of an almost Hermitian manifold \bar{M} is said to be a *totally umbilical submanifold* if the second fundamental form satisfies

$$h(X, Y) = g(X, Y)H \quad (2.7)$$

for all $X, Y \in TM$. The submanifold M is *totally geodesic* if $h(X, Y) = 0$, for all $X, Y \in TM$ and minimal if $H = 0$.

For any $X \in TM$ and $N \in T^\perp M$, the transformations JX and JN are decomposed into tangential and normal parts respectively as

$$JX = TX + FX \tag{2.8}$$

$$JN = BN + CN. \tag{2.9}$$

Now, denote by $\mathcal{P}_X Y$ and $\mathcal{Q}_X Y$ the tangential and normal parts of $(\bar{\nabla}_X J)Y$, respectively. That is,

$$(\bar{\nabla}_X J)Y = \mathcal{P}_X Y + \mathcal{Q}_X Y \tag{2.10}$$

for all $X, Y \in TM$. Making use of equations (2.8), (2.9) and the Gauss and Weingarten formulae, the following equations may be obtained easily.

$$\mathcal{P}_X Y = (\bar{\nabla}_X T)Y - A_{FY}X - Bh(X, Y) \tag{2.11}$$

$$\mathcal{Q}_X Y = (\bar{\nabla}_X F)Y + h(X, TY) - Ch(X, Y) \tag{2.12}$$

Similarly, for any $N \in T^\perp M$, denoting tangential and normal parts of $(\bar{\nabla}_X J)N$ by $\mathcal{P}_X N$ and $\mathcal{Q}_X N$ respectively, we obtain

$$\mathcal{P}_X N = (\bar{\nabla}_X B)N + TA_N X - A_{CN} X \tag{2.13}$$

$$\mathcal{Q}_X N = (\bar{\nabla}_X C)N + h(BN, X) + FA_N X \tag{2.14}$$

where the covariant derivatives of T , F , B and C are defined by

$$(\bar{\nabla}_X T)Y = \nabla_X TY - T\nabla_X Y \tag{2.15}$$

$$(\bar{\nabla}_X F)Y = \nabla_X^\perp FY - F\nabla_X Y \tag{2.16}$$

$$(\bar{\nabla}_X B)N = \nabla_X BN - B\nabla_X^\perp N \tag{2.17}$$

$$(\bar{\nabla}_X C)N = \nabla_X^\perp CN - C\nabla_X^\perp N \tag{2.18}$$

for all $X, Y \in TM$ and $N \in T^\perp M$.

It is straightforward to verify the following properties of \mathcal{P} and \mathcal{Q} , which we enlist here for later use:

- (p₁) (i) $\mathcal{P}_{X+Y}W = \mathcal{P}_X W + \mathcal{P}_Y W$, (ii) $\mathcal{Q}_{X+Y}W = \mathcal{Q}_X W + \mathcal{Q}_Y W$,
- (p₂) (i) $\mathcal{P}_X(Y+W) = \mathcal{P}_X Y + \mathcal{P}_X W$, (ii) $\mathcal{Q}_X(Y+W) = \mathcal{Q}_X Y + \mathcal{Q}_X W$,
- (p₃) (i) $g(\mathcal{P}_X Y, W) = -g(Y, \mathcal{P}_X W)$, (ii) $g(\mathcal{Q}_X Y, N) = -g(Y, \mathcal{P}_X N)$,

$$(p_4) \quad \mathcal{P}_X JY + \mathcal{Q}_X JY = -J(\mathcal{P}_X Y + \mathcal{Q}_X Y)$$

for all $X, Y, W \in TM$ and $N \in T^\perp M$.

On a submanifold M of a nearly Kaehler manifold, by equations (2.2) and (2.10), we have

$$(a) \quad \mathcal{P}_X Y + \mathcal{P}_Y X = 0, \quad (b) \quad \mathcal{Q}_X Y + \mathcal{Q}_Y X = 0 \quad (2.19)$$

for any $X, Y \in TM$.

The submanifold M is said to be *holomorphic* if F is identically zero, that is, $\phi X \in TM$ for any $X \in TM$. On the other hand, M is said to be *totally real* if T is identically zero, that is $\phi X \in T^\perp M$, for any $X \in TM$.

A distribution D on a submanifold M of an almost Hermitian manifold \bar{M} is said to be a *slant distribution* if for each $X \in D_x$, the angle θ between JX and D_x is constant i.e., independent of $x \in M$ and $X \in D_x$. In this case, a submanifold M of \bar{M} is said to be a *slant submanifold* if the tangent bundle TM of M is slant.

Moreover, for a slant distribution D , we have

$$T^2 X = -\cos^2 \theta X \quad (2.20)$$

for any $X \in D$. The following relations are straightforward consequences of equation (2.20):

$$g(TX, TY) = \cos^2 \theta g(X, Y) \quad (2.21)$$

$$g(FX, FY) = \sin^2 \theta g(X, Y) \quad (2.22)$$

for all $X, Y \in D$.

A submanifold M of an almost Hermitian manifold \bar{M} is said to be a *pseudo-slant submanifold* if there exist two orthogonal complementary distributions D_1 and D_2 satisfying:

$$(i) \quad TM = D_1 \oplus D_2$$

$$(ii) \quad D_1 \text{ is a slant distribution with slant angle } \theta \neq \pi/2$$

$$(iii) \quad D_2 \text{ is totally real i.e., } JD_2 \subseteq T^\perp M.$$

A pseudo-slant submanifold M of an almost Hermitian manifold \bar{M} is *mixed geodesic* if

$$h(X, Z) = 0 \quad (2.23)$$

for any $X \in D_1$ and $Z \in D_2$.

If μ is the invariant subspace of the normal bundle $T^\perp M$, then in the case of pseudo-slant submanifold, the normal bundle $T^\perp M$ can be decomposed as follows:

$$T^\perp M = \mu \oplus FD_1 \oplus FD_2. \quad (2.24)$$

3 Warped product pseudo-slant submanifolds

In 1969 Bishop and O’Neill [1] introduced the notion of warped product manifolds. These manifolds are natural generalizations of Riemannian product manifolds. They defined these manifolds as: Let (N_1, g_1) and (N_2, g_2) be two Riemannian manifolds and f , a positive differentiable function on N_1 . The warped product of N_1 and N_2 is the Riemannian manifold $N_1 \times_f N_2 = (N_1 \times N_2, g)$, where

$$g = g_1 + f^2 g_2. \tag{3.1}$$

A warped product manifold $N_1 \times_f N_2$ is said to be *trivial* if the warping function f is constant. We recall the following general formula on a warped product [1].

$$\nabla_X Z = \nabla_Z X = (X \ln f)Z, \tag{3.2}$$

where X is tangent to N_1 and Z is tangent to N_2 .

Let $M = N_1 \times_f N_2$ be a warped product manifold. This means that N_1 is totally geodesic and N_2 is a totally umbilical submanifold of M [1].

Throughout this section, we consider warped product pseudo-slant submanifolds which are either in the form $N_\perp \times_f N_\theta$ or $N_\theta \times_f N_\perp$ in a nearly Kaehler manifold \bar{M} , where N_θ and N_\perp are proper slant and totally real submanifolds of \bar{M} , respectively. In the following theorem we consider the warped product pseudo-slant submanifolds in the form $M = N_\perp \times_f N_\theta$ of a nearly Kaehler manifold \bar{M} .

Theorem 3.1. *Let \bar{M} be a nearly Kaehler manifold. Then the warped product submanifold $M = N_\perp \times_f N_\theta$ is a Riemannian product of N_\perp and N_θ if and only if $\mathcal{P}_X TX$ lies in TN_θ , for any $X \in TN_\theta$, where N_\perp and N_θ are totally real and proper slant submanifolds of \bar{M} , respectively.*

Proof. Let $M = N_\perp \times_f N_\theta$ be a warped product pseudo-slant submanifold of a nearly Kaehler manifold \bar{M} . For any $X \in TN_\theta$ and $W \in TN_\perp$, we have

$$g(h(TX, W), FX) = g(\bar{\nabla}_W TX, FX) = -g(TX, \bar{\nabla}_W FX).$$

Using (2.8), we derive

$$g(h(TX, W), FX) = g(TX, \bar{\nabla}_W TX) - g(TX, \bar{\nabla}_W JX).$$

Then from (2.3) and the covariant derivative property of J , we obtain

$$g(h(TX, W), FX) = g(TX, \nabla_W TX) - g(TX, (\bar{\nabla}_W J)X) - g(TX, J\bar{\nabla}_W X).$$

Thus, using (2.1), (2.10) and (3.2) we get

$$g(h(TX, W), FX) = (W \ln f)g(TX, TX) - g(TX, \mathcal{P}_W X) + g(JTX, \bar{\nabla}_W X).$$

Using (2.3), (2.8), (2.19) (a) and (2.21), we obtain

$$\begin{aligned} g(h(TX, W), FX) &= (W \ln f) \cos^2 \theta \|X\|^2 + g(TX, \mathcal{P}_X W) \\ &\quad + g(T^2 X, \nabla_W X) + g(h(X, W), FTX). \end{aligned}$$

Thus by property p_3 (i), (2.20) and (3.2), we derive

$$\begin{aligned} g(h(TX, W), FX) &= (W \ln f) \cos^2 \theta \|X\|^2 - g(\mathcal{P}_X TX, W) \\ &\quad - (W \ln f) \cos^2 \theta \|X\|^2 + g(h(X, W), FTX). \end{aligned}$$

Hence the above equation takes the form

$$g(\mathcal{P}_X TX, W) = g(h(X, W), FTX) - g(h(TX, W), FX). \quad (3.3)$$

On the other hand for any $X \in TN_\theta$ and $W \in TN_\perp$, we have

$$g(h(X, TX), JW) = g(\bar{\nabla}_{TX} X, JW) = -g(J\bar{\nabla}_{TX} X, W).$$

Using the covariant differentiation formula of J , we get

$$g(h(X, TX), JW) = g((\bar{\nabla}_{TX} J)X, W) - g(\bar{\nabla}_{TX} JX, W).$$

Then by (2.10) and property of $\bar{\nabla}$, we derive

$$g(h(X, TX), JW) = g(\mathcal{P}_{TX} X, W) + g(JX, \bar{\nabla}_{TX} W).$$

Thus from (2.3), (2.8) and (2.19) (a), we obtain

$$g(h(X, TX), JW) = -g(\mathcal{P}_X TX, W) + g(TX, \nabla_{TX} W) + g(h(TX, W), FX).$$

By (3.2), the above equation reduces to

$$\begin{aligned} g(h(X, TX), JW) &= -g(\mathcal{P}_X TX, W) \\ &\quad + (W \ln f)g(TX, TX) + g(h(TX, W), FX). \end{aligned}$$

Hence, using (2.21), we get

$$\begin{aligned} g(h(X, TX), JW) &= -g(\mathcal{P}_X TX, W) + (W \ln f) \cos^2 \theta \|X\|^2 \\ &\quad + g(h(TX, W), FX). \end{aligned} \quad (3.4)$$

By property (p_3) (i), the above equation reduces to

$$g(h(X, TX), JW) = g(TX, \mathcal{P}_X W) + (W \ln f) \cos^2 \theta \|X\|^2 + g(h(TX, W), FX).$$

Interchanging X with TX and then using (2.20) and (2.21), we obtain

$$-\cos^2 \theta g(h(X, TX), JW) = -\cos^2 \theta g(X, \mathcal{P}_{TX} W) + (W \ln f) \cos^4 \theta g(X, X) - \cos^2 \theta g(h(X, W), FTX).$$

Again, by first using property (p_3) (i) followed by (2.19) (a) we arrive at

$$-g(h(X, TX), JW) = -g(\mathcal{P}_X TX, W) + (W \ln f) \cos^2 \theta \|X\|^2 - g(h(X, W), FTX). \tag{3.5}$$

Then from (3.4) and (3.5), we obtain

$$2(W \ln f) \cos^2 \theta \|X\|^2 = 2g(\mathcal{P}_X TX, W) + g(h(X, W), FTX) - g(h(TX, W), FX). \tag{3.6}$$

Thus, by (3.3) and (3.6), we conclude that

$$(W \ln f) \cos^2 \theta \|X\|^2 = \frac{3}{2}g(\mathcal{P}_X TX, W). \tag{3.7}$$

Since N_θ is proper slant, thus we get $(W \ln f) = 0$, if and only if $\mathcal{P}_X TX$ lies in TN_θ for all $X \in TN_\theta$ and $W \in TN_\perp$. This shows that f is constant on N_\perp . The proof is thus complete. \square

Theorem 3.2. *The warped product submanifold $M = N_\theta \times_f N_\perp$ of a nearly Kaehler manifold \bar{M} is simply a Riemannian product of N_θ and N_\perp if and only if*

$$g(h(X, Z), FZ) = g(h(Z, Z), FX), \tag{3.7}$$

for any $X \in TN_\theta$ and $Z \in TN_\perp$, where N_θ and N_\perp are proper slant and totally real submanifolds of \bar{M} , respectively.

Proof. Let $M = N_\theta \times_f N_\perp$ be a warped product submanifold of a nearly Kaehler manifold \bar{M} . Then for any $X \in TN_\theta$ and $Z \in TN_\perp$, we have

$$g(h(TX, Z), FZ) = g(\bar{\nabla}_Z TX, JZ).$$

Using (2.1), we get

$$g(h(TX, Z), FZ) = -g(J\bar{\nabla}_Z TX, Z).$$

Thus, on using the covariant differentiation property of J , we obtain

$$g(h(TX, Z), FZ) = g((\bar{\nabla}_Z J)TX, Z) - g(\bar{\nabla}_Z JTX, Z).$$

Then from (2.8) and (2.10), we derive

$$g(h(TX, Z), FZ) = g(\mathcal{P}_Z TX, Z) - g(\bar{\nabla}_Z T^2 X, Z) - g(\bar{\nabla}_Z FTX, Z).$$

Now, using (2.4), (p_3) (i) and (2.20) we obtain that

$$g(h(TX, Z), FZ) = -g(\mathcal{P}_Z Z, TX) + \cos^2 \theta g(\nabla_Z X, Z) + g(A_{FTX} Z, Z).$$

Since on using (2.2) and (2.10) we have $\mathcal{P}_Z Z = 0$, then from (2.5) and (3.2), we get

$$g(h(TX, Z), FZ) = (X \ln f) \cos^2 \theta \|Z\|^2 + g(h(Z, Z), FTX). \quad (3.8)$$

Interchanging X with TX in (3.8), we obtain

$$\cos^2 \theta g(h(X, Z), FZ) = -(TX \ln f) \cos^2 \theta \|Z\|^2 + \cos^2 \theta g(h(Z, Z), FX).$$

The above equation can be written as

$$(TX \ln f) \|Z\|^2 = g(h(Z, Z), FX) - g(h(X, Z), FZ). \quad (3.9)$$

Thus, $(TX \ln f) = 0$ if and only if $g(h(Z, Z), FX) = g(h(X, Z), FZ)$. This proves the theorem. \square

The following corollaries are consequences of the above theorem.

Corollary 3.1. *There does not exist any warped product pseudo-slant submanifolds $M = N_\theta \times_f N_\perp$ of a nearly Kaehler manifold \bar{M} , if the condition*

$$h(TM, D^\perp) \in \mu,$$

holds, where μ is the invariant normal subbundle of TM and D^\perp is a distribution corresponding to the submanifold N_\perp .

Proof. The proof follows from (3.9). \square

Corollary 3.2. *There does not exist any mixed totally geodesic pseudo-slant warped product submanifold $M = N_\theta \times_f N_\perp$ of a nearly Kaehler manifold \bar{M} such that $h(Z, Z) \in \mu$ for all $Z \in D^\perp$.*

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